

## Inverse Geodetic Problem: Computing $\phi$ , $\lambda$ , $h$ given $X$ , $Y$ , $Z$ Solution From Torge

### Some useful Angle Functions

$\text{dd}(\text{ang}) := \left\{ \begin{array}{l} \text{degree} \leftarrow \text{floor}(\text{ang}) \\ \text{mins} \leftarrow (\text{ang} - \text{degree}) \cdot 100.0 \\ \text{minutes} \leftarrow \text{floor}(\text{mins}) \\ \text{seconds} \leftarrow (\text{mins} - \text{minutes}) \cdot 100.0 \\ \text{degree} + \frac{\text{minutes}}{60.0} + \frac{\text{seconds}}{3600.0} \end{array} \right.$	$\text{radians}(\text{ang}) := \left\{ \begin{array}{l} \text{d} \leftarrow \text{dd}(\text{ang}) \\ \text{d} \cdot \frac{\pi}{180.0} \end{array} \right.$
$\text{r2d} := \frac{180}{\pi}$	$\text{dms}(\text{ang}) := \left\{ \begin{array}{l} \text{degree} \leftarrow \text{floor}(\text{ang}) \\ \text{rem} \leftarrow (\text{ang} - \text{degree}) \cdot 60 \\ \text{mins} \leftarrow \text{floor}(\text{rem}) \\ \text{rem1} \leftarrow (\text{rem} - \text{mins}) \\ \text{secs} \leftarrow \text{rem1} \cdot 60.0 \\ \text{degree} + \frac{\text{mins}}{100} + \frac{\text{secs}}{10000} \end{array} \right.$

From the Geodetic Reference System 1980:

$$a := 6378137\text{m}$$

$$e_2 := 0.00669438002290$$

Given the following Cartesian Coordinates:

$$X := 354327.587\text{m}$$

$$Y := -4606955.685\text{m}$$

$$Z := 4382483.757\text{m}$$

#### Solution

$$\lambda := \left( \text{atan} \left( \frac{Y}{X} \right) \right) \quad l := \text{if}(\lambda < 0, -1, 1)$$

The longitude of the point is:

$$l \text{ dms}(|\lambda| \cdot \text{r2d}) = -85.360704728$$

iterate  $\phi$

$$\phi_1 := \left( \text{atan} \left( \frac{Z}{\sqrt{X^2 + Y^2}} \right) \right)$$

The value  $\phi_1$  represents the current estimate of the latitude. Here it is the initial estimate.

$$N := \frac{a}{\sqrt{1 - e_2 \cdot (\sin(\phi_1))^2}}$$

$N$  is the radius of curvature in the prime vertical

$$N = 6388271.36419801 \text{ m}$$

$$h := 0\text{m}$$

The initial estimate of the height is taken as zero.

$$\phi := \left[ \text{atan} \left[ \left( \frac{Z}{\sqrt{X^2 + Y^2}} \right) \cdot \left( 1 - e_2 \cdot \frac{N}{N + h} \right)^{-1} \right] \right]$$

$$\text{dms}(\phi \cdot r2d) = 43.403865442$$

$$\phi - \phi_1 = 0.00335432$$

Test to see how close the current estimate of the latitude is to the estimate used to determine the current estimate

$$\Delta\phi := (\phi - \phi_1) \cdot r2d$$

$$\text{dms}(|\Delta\phi|) = 0.1131878238$$

$$\Delta\phi = 0.1921883995$$

$$\phi_1 := \phi$$

Updating the current estimate to the value just computed.

$$h := \frac{\sqrt{X^2 + Y^2}}{\cos(\phi)} - N$$

h is updated with a new value based on the value for the latitude.

$$h = 429.968746328\text{ m}$$

Iteration No. 2

$$N := \frac{a}{\sqrt{1 - e_2 \cdot (\sin(\phi_1))^2}}$$

$$N = 6388343.22979735\text{ m}$$

$$\phi := \left[ \text{atan} \left[ \left( \frac{Z}{\sqrt{X^2 + Y^2}} \right) \cdot \left( 1 - e_2 \cdot \frac{N}{N + h} \right)^{-1} \right] \right]$$

$$\text{dms}(\phi \cdot r2d) = 43.40386077$$

$$\phi - \phi_1 = -0.000000227 \quad \Delta\phi := (\phi - \phi_1) \cdot r2d$$

$$\text{dms}(|\Delta\phi|) = 0.000004673$$

$$\phi_1 := \phi$$

$$h := \frac{\sqrt{X^2 + Y^2}}{\cos(\phi)} - N$$

$$h = 356.72114\text{ m}$$

Iteration No. 3

$$N := \frac{a}{\sqrt{1 - e_2 \cdot (\sin(\phi_1))^2}}$$

$$N = 6388343.22494281\text{ m}$$

$$\phi := \left[ \operatorname{atan} \left[ \left( \frac{Z}{\sqrt{X^2 + Y^2}} \right) \cdot \left( 1 - e_2 \cdot \frac{N}{N + h} \right)^{-1} \right] \right]$$

$$\operatorname{dms}(\phi \cdot r2d) = 43.403861566$$

$$\phi - \phi_1 = 0.000000039$$

$$\Delta\phi := (\phi - \phi_1) \cdot r2d$$

$$\operatorname{dms}(|\Delta\phi|) = 0.000000796$$

$$\phi_1 := \phi$$

$$h := \frac{\sqrt{X^2 + Y^2}}{\cos(\phi)} - N$$

$$h = 356.96142 \text{ m}$$

Iteration No.4

$$N := \frac{a}{\sqrt{1 - e_2 \cdot (\sin(\phi_1))^2}}$$

$$N = 6388343.22576977 \text{ m}$$

$$\phi := \left[ \operatorname{atan} \left[ \left( \frac{Z}{\sqrt{X^2 + Y^2}} \right) \cdot \left( 1 - e_2 \cdot \frac{N}{N + h} \right)^{-1} \right] \right]$$

The latitude of the point is:

$$\operatorname{dms}(\phi \cdot r2d) = 43.403861563$$

$$\phi - \phi_1 = -0$$

$$\Delta\phi := (\phi - \phi_1) \cdot r2d$$

$$\operatorname{dms}(|\Delta\phi|) = 0.000000003$$

$$h := \frac{\sqrt{X^2 + Y^2}}{\cos(\phi)} - N$$

The height of the point is:

$$h = 356.95982 \text{ m}$$